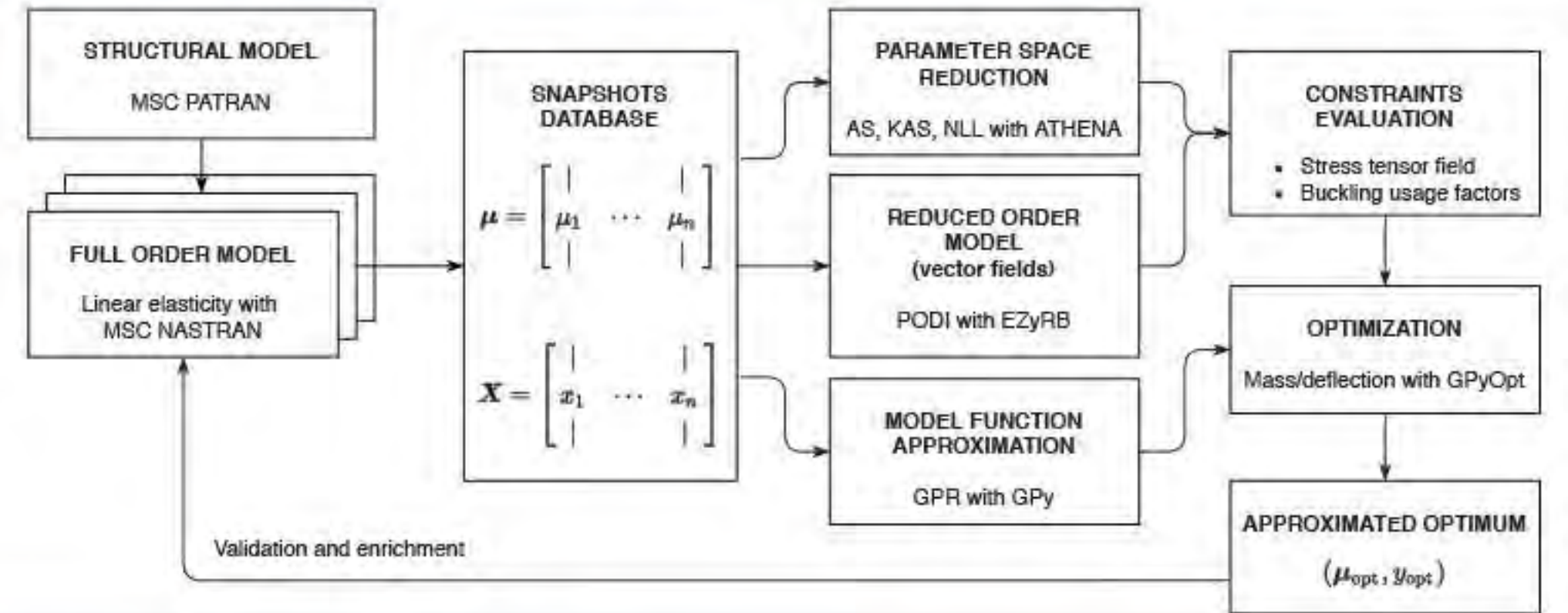


Structural optimization pipeline based on Reduced Order Methods (ROMs)

We present a structural optimization computational pipeline. We exploit MSC Patran and MSC Nastran softwares to create a solutions database for different input parameters. Then we apply non-intrusive Reduced Order Methods (ROMs) such as **Proper Orthogonal Decomposition with Interpolation (PODI)** to predict the solution fields of interest, and **Active Subspaces (AS)** to reduce the parameter space dimensionality and perform sensitivity analysis over the parameters, using open source Python packages. Finally Bayesian optimization is employed to minimize a target scalar function while ROMs serve as enablers for fast and accurate real-time evaluations.

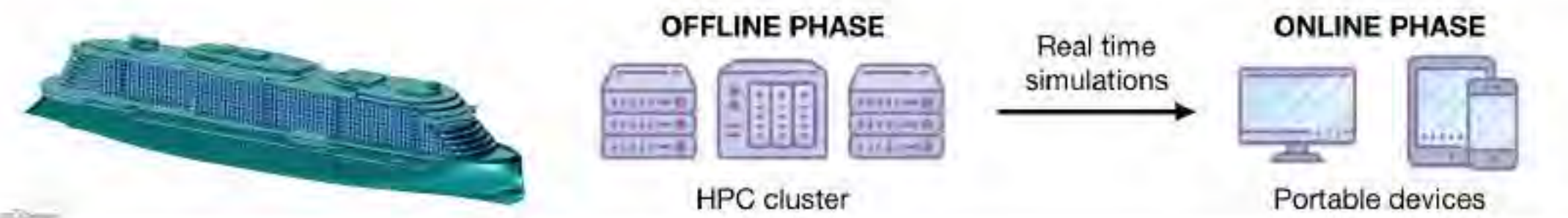


1 - Proper Orthogonal Decomposition with Interpolation (PODI) [3]

POD with interpolation main features:

- No need to know the underlying equations/matrices (as for POD-Galerkin method).
- SVD of the snapshots matrix $X = U\Sigma V^*$.
- Using the first N modes U_N , we are able to span the low-dimensional space on which we project the original samples.
- The modal coefficients are computed as $C = U_N^T X$.

- Real-time computation of the solution fields for any new parameter by interpolating the modal coefficients
- **Offline-online paradigm** allows to efficiently exploit all the collected simulations to make **real-time predictions** (moreover we can enrich the database!)



2 - Active Subspaces (AS) [1, 2]

Consider a function, its gradient vector, and a sampling p.d.f.

$$f = f(x), \quad x \in \mathbb{R}^m, \quad \nabla f(x) \in \mathbb{R}^m, \quad \rho: \mathbb{R}^m \rightarrow \mathbb{R}_+$$

Take the average outer product of the gradients and partition its eigendecomposition,

$$C = \mathbb{E}[\nabla_x f \nabla_x f^T] = \int (\nabla_x f)(\nabla_x f)^T \rho dx = W\Lambda W^T$$

$$\Lambda = \begin{bmatrix} \Lambda_1 & \\ & \Lambda_2 \end{bmatrix}, \quad W = [W_1 \quad W_2], \quad W_1 \in \mathbb{R}^{m \times n}$$

Rotate and separate the coordinates:

$$x = WW^T x = W_1 W_1^T x + W_2 W_2^T x = W_1 y + W_2 z$$

We call y the active variable and z the inactive one:

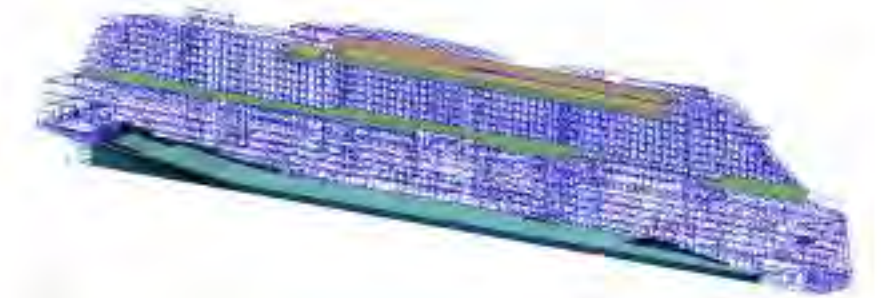
$$y = W_1^T x \in \mathbb{R}^n, \quad z = W_2^T x \in \mathbb{R}^{m-n}$$



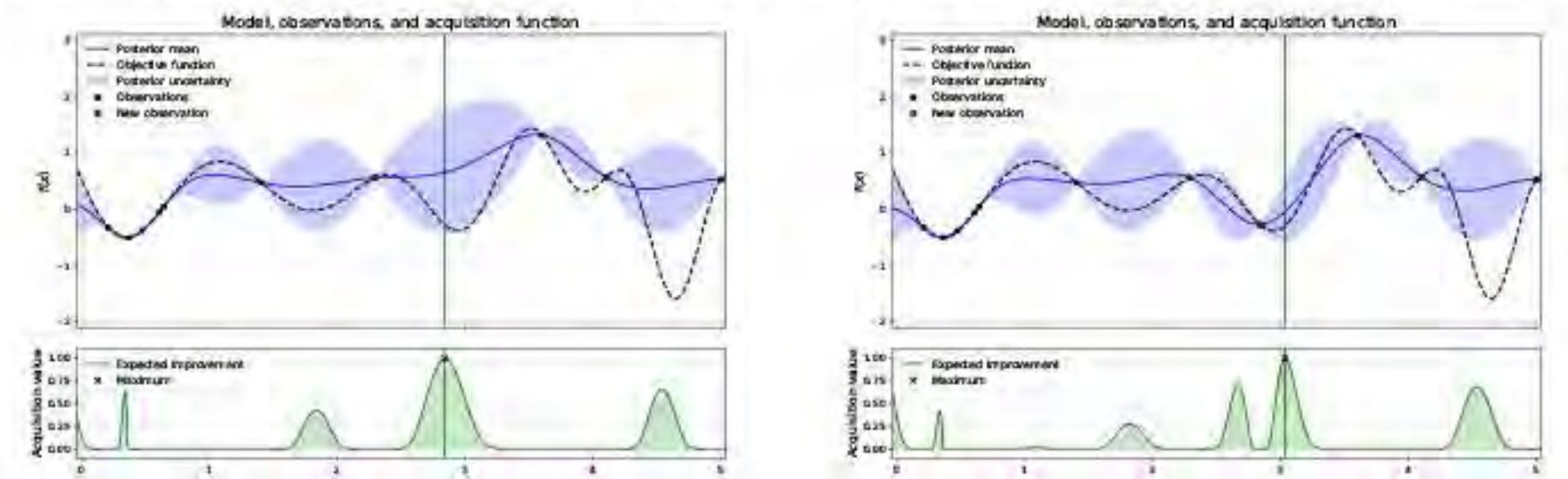
3 - Bayesian optimization

We seek a global minimizer of an unknown function of interest using a Bayesian optimization approach

$$x_{opt} = \arg \min_{x \in \Omega} f(x)$$

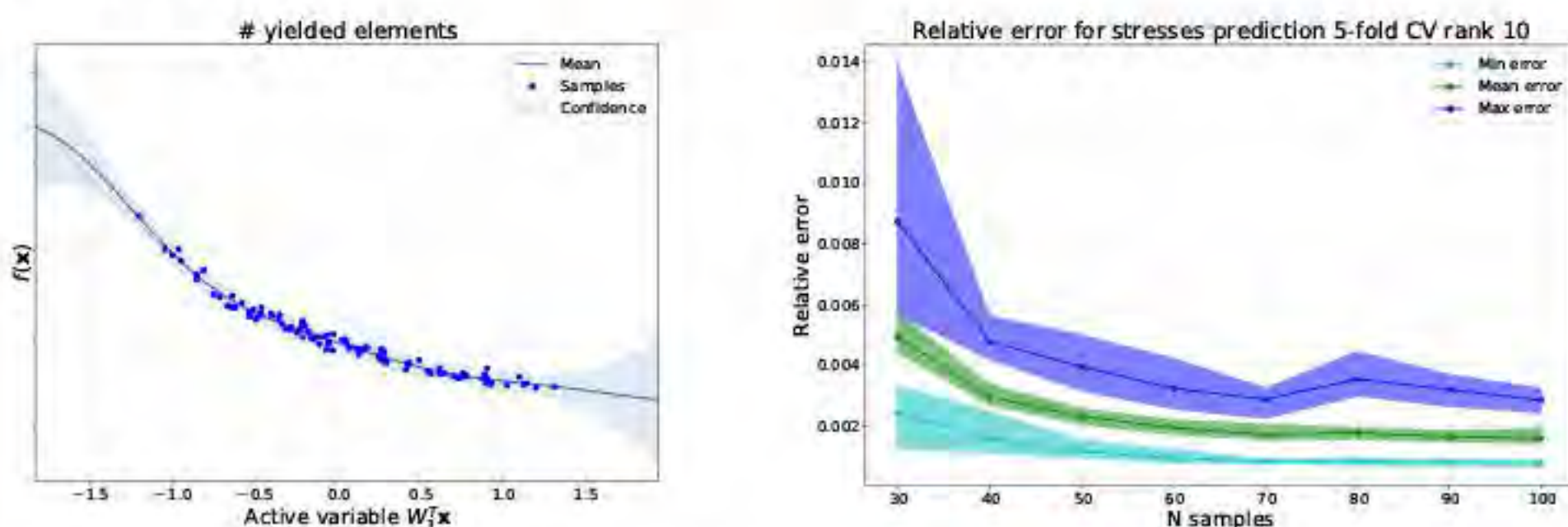
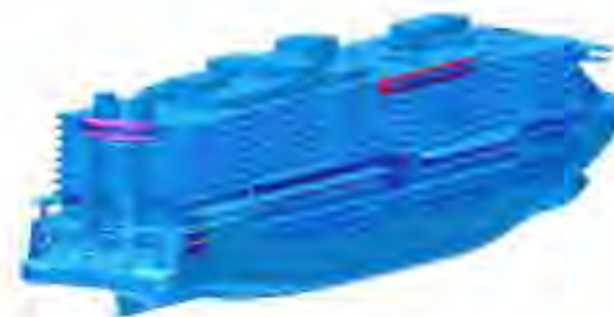


We maximize the **Expected Improvement** acquisition function, depicted in green below with an illustrative example, to select the next sample to evaluate. Our design inputs are the thickness of 6 regions of the hull.



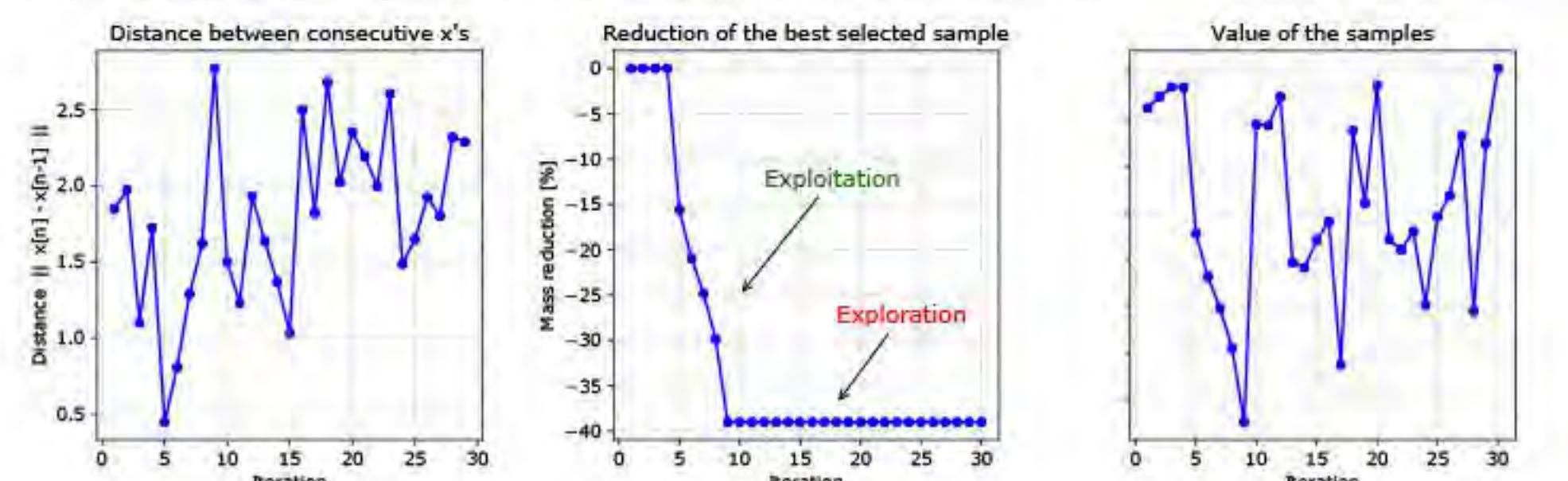
4 - Solution fields and constraints prediction

Using PODI we predict the stress tensor field for new parameters with an L^2 relative error smaller than 0.3%. Constraints such as the number of yielded or buckled elements are evaluated through GP regression over the active subspace.



5 - Numerical results

We minimize the mass of the parametrized decks of the hull, under the constraints of a prescribed maximum number of yielded and buckled elements, for a given load condition. We achieve very good results. ROMs are used to reconstruct the stress tensor and the buckling usage factors fields for new untried parameters in real-time. AS is employed to reduce the number of parameters for the constraints evaluation.



References and Acknowledgements

[1] P. G. Constantine. *Active subspaces: Emerging ideas for dimension reduction in parameter studies*, volume 2 of *SIAM Spotlights*. SIAM, 2015.

[2] N. Demo, M. Tezzele, and G. Rozza. A non-intrusive approach for reconstruction of POD modal coefficients through active subspaces. *Comptes Rendus Mécanique de l'Académie des Sciences, DataBEST 2019 Special Issue*, 347(11):873–881, November 2019.

[3] M. Tezzele, N. Demo, A. Mola, and G. Rozza. An integrated data-driven computational pipeline with model order reduction for industrial and applied mathematics. *Special Volume ECMI, In Press*, 2020.

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